Sensitivity analysis: tutorial

Alen Alexanderian (NC State)
 Pierre Gremaud (NC State)

July 26, 2018 Workshop on Parameter Estimation for Biological Models

Goal

model:
$$y = f(x_1, \ldots, x_p)$$

- response y
- \blacktriangleright inputs x_1, \ldots, x_p

we want to:

quantify how uncertainties in the model response can be apportioned to uncertainties in model inputs

< □ > < 同 > < Ξ > < Ξ > < Ξ > < Ξ < </p>

the larger the contribution, the more important the input

Challenges

- no agreement on the meaning of important
- ▶ one SA method ⇔ one definition of "importance"
- f may be
 - a black box (computer code/executable)
 - expensive to evaluate (\Rightarrow few values are available)

< □ > < 同 > < Ξ > < Ξ > < Ξ > < Ξ < </p>

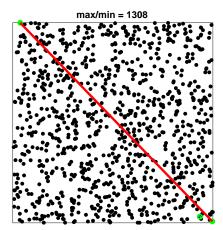
p may be large (high dimensional problem)

it is expensive; GSA can be used to reduced parameter space dimension (inspired by P. Constantine)

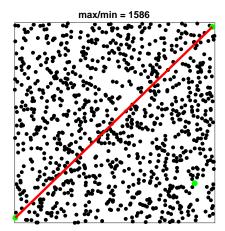
# of parameters ρ	# of model runs	time per run
(the dimension)	(10 points per dim)	(1 sec per run)
1	10	10 sec
2	100	1.7 min
3	1,000	17 min
4	10,000	2.8 hrs
5	100,000	28 hrs
6	1,000,000	12 days
10	10 ¹⁰	317 years
20	10 ²⁰	3 trillion years
		230 \times age of universe

dimension reduction IS your friend

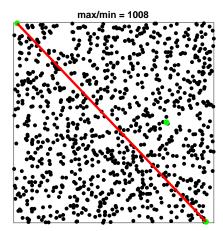
- draw 1000 points from $U([0, 1]^p)$
- compute (max distance between 2 points)/(min distance between 2 points)



- draw 1000 points from $U([0, 1]^p)$
- compute (max distance between 2 points)/(min distance between 2 points)

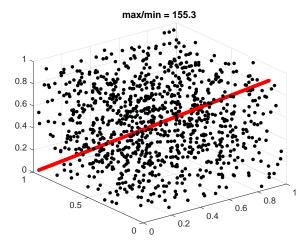


- draw 1000 points from $U([0, 1]^p)$
- compute (max distance between 2 points)/(min distance between 2 points)



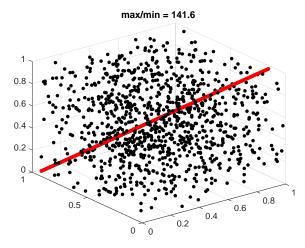
measuring distances gets hard (inspired by Beyer et al. 1999)

- draw 1000 points from $U([0, 1]^p)$
- compute (max distance between 2 points)/(min distance between 2 points)



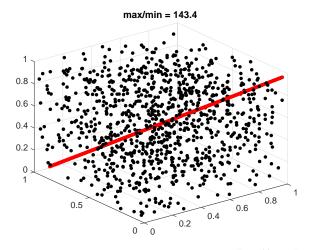
) ≥

- draw 1000 points from $U([0, 1]^p)$
- compute (max distance between 2 points)/(min distance between 2 points)



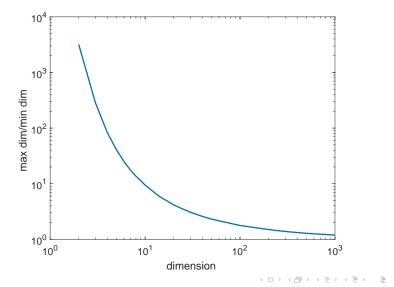
measuring distances gets hard (inspired by Beyer et al. 1999)

- draw 1000 points from $U([0, 1]^p)$
- compute (max distance between 2 points)/(min distance between 2 points)



E 990

 \triangleright $\forall p$, results from 100 sets of 1000 points are averaged



900

the geometry gets weird

- unit (hyper-)spheres and (hyper-)cubes centered at 0
- distance 0-vertex: p = 2

$$\sqrt{\left(rac{1}{2}
ight)^2+\left(rac{1}{2}
ight)^2}=rac{1}{\sqrt{2}}pprox 0.707<1$$
 inside the sphere

distance 0-vertex: p = 4

$$\sqrt{\left(\frac{1}{2}\right)^2 + \left(\frac{1}{2}\right)^2 + \left(\frac{1}{2}\right)^2 + \left(\frac{1}{2}\right)^2} = 1 \qquad \text{on the sphere}$$

• distance 0-vertex: in general = $\frac{\sqrt{p}}{2}$

 \Rightarrow (way) outside the sphere for p > 4; $p = 400 \Rightarrow$ dist = 10

A D F A 同 F A E F A E F A Q A

What kind of model do you have?

- diagnostics (understanding) vs. prognostics (predictions)
- ► data-driven vs. law-driven
- law-driven models are good for understanding but are generally overparametrized

◆□▶ ◆□▶ ▲□▶ ▲□▶ □ のQ@

Overparametrization is bad

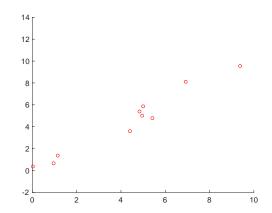
- makes you work in a needlessly high-dimensional space
- loses predictive power

In desperation I asked Fermi whether he was not impressed by the agreement between our calculated numbers and his measured numbers. He replied, "How many arbitrary parameters did you use for your calculations?" I thought for a moment about our cut-off procedures and said, "Four." He said, "I remember my friend Johnny von Neumann used to say, with four parameters I can fit an elephant, and with five I can make him wiggle his trunk."

Freeman Dyson

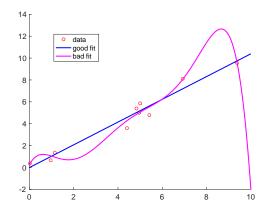
Overparametrization is bad

- makes you work in a needlessly high-dimensional space
- loses predictive power
- easily leads to overfitting



Overparametrization is bad

- makes you work in a needlessly high-dimensional space
- loses predictive power
- easily leads to overfitting



< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Rationale for SA (inspired by Saltelli)

- model corroboration: is the inference robust?
- research prioritization: which factor most deserves further analysis/measurement?
- model simplification: can factors/compartments be fixed or simplified?

(ロ) (同) (三) (三) (三) (○) (○)

 model reliability: identify factors which interact and may lead to extreme values

Elementary (linear) example (I)

$$y = f(x_1, x_2) = ax_1 + bx_2, \quad a, b > 0$$

1. calculus:

$$S_i = \frac{\partial y}{\partial x_i}, i = 1, 2 \quad \Rightarrow \quad S_1 = a, S_2 = b$$

problems with this approach:

- ignore range of values for x₁ and x₂
- for f nonlinear, this is a local approach (the derivatives have to be evaluated somewhere)
- need to be able to compute derivatives (problematic for black box functions)

Elementary (linear) example (II) 2. Sobol':



 considers x_i's as random variables; for instance

$$x_i \sim N(0, \sigma_i^2)$$

 apportion to them their relative contribution to the variance of the response

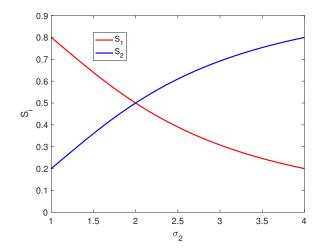
• with above distributions: $y \sim N(0, \sigma_Y^2)$

$$\sigma_{Y}^{2} = a^{2}\sigma_{1}^{2} + b^{2}\sigma_{2}^{2} \Rightarrow 1 = \underbrace{\frac{a^{2}\sigma_{1}^{2}}{a^{2}\sigma_{1}^{2} + b^{2}\sigma_{2}^{2}}}_{S_{1}} + \underbrace{\frac{b^{2}\sigma_{2}^{2}}{a^{2}\sigma_{1}^{2} + b^{2}\sigma_{2}^{2}}}_{S_{2}}$$

▶ note the importance of the σ_i 's!

Elementary (linear) example (III)

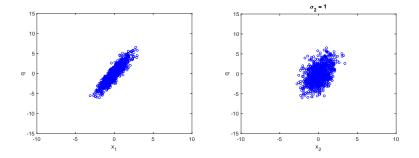
Let's take $a = 2, b = 1, \sigma_1 = 1 \Rightarrow S_1 = \frac{4}{4+\sigma_2^2}$ and $S_2 = \frac{\sigma_2^2}{4+\sigma_2^2}$.



▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

Elementary (linear) example (IV)

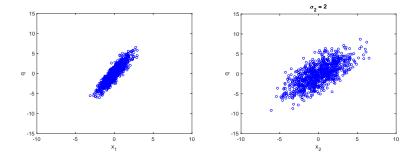
Let's take
$$a = 2$$
, $b = 1$, $\sigma_1 = 1 \Rightarrow S_1 = \frac{4}{4+\sigma_2^2}$ and $S_2 = \frac{\sigma_2^2}{4+\sigma_2^2}$.



▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

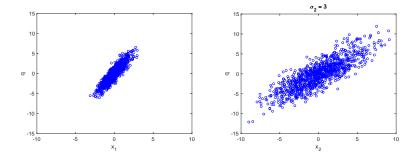
Elementary (linear) example (IV)

Let's take
$$a = 2$$
, $b = 1$, $\sigma_1 = 1 \Rightarrow S_1 = \frac{4}{4+\sigma_2^2}$ and $S_2 = \frac{\sigma_2^2}{4+\sigma_2^2}$.



Elementary (linear) example (IV)

Let's take
$$a = 2$$
, $b = 1$, $\sigma_1 = 1 \Rightarrow S_1 = \frac{4}{4+\sigma_2^2}$ and $S_2 = \frac{\sigma_2^2}{4+\sigma_2^2}$



Sobol' indices: same idea for general case

- how about using var(y|x_i = x_i^{*}) to build an importance measure of x_i?
- not a good idea!

▶ fi

- ▶ answer would depend on x_i^* (⇒ local)
- it can be that $var(y|x_i = x_i^*) > var(y)!$
- both issues disappear upon averaging

 $\mathbb{E}_{x_i}[\mathsf{var}_{x_{\sim i}}(y|x_i)]$

indeed by the law of total variance

$$\bigstar \quad \operatorname{var}_{x_i}(\mathbb{E}_{x_{\sim i}}[y|x_i]) + \mathbb{E}_{x_i}[\operatorname{var}_{x_{\sim i}}(y|x_i)] = \operatorname{var}(y)$$
rst order index: $S_i = \frac{\operatorname{var}(\mathbb{E}[y|x_i])}{\operatorname{var}(y)}$

(日) (日) (日) (日) (日) (日) (日)

First order Sobol' indices

▶ first order index: $S_i = \frac{\operatorname{var}(\mathbb{E}[y|x_i])}{\operatorname{var}(y)}, i = 1, \dots, p$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

▶
$$0 \le S_i \le 1, i = 1, ..., p$$

▶
$$S_i$$
 "close" to 1 \Rightarrow x_i important

► S_i "small" $\neq x_i$ is not important

Total Sobol' indices

Using again (\bigstar) but with $x_{\sim i}$ instead of x_i

$$\mathsf{var}(\mathbb{E}[y|x_{\sim i}]) + \mathbb{E}[\mathsf{var}(y|x_{\sim i})] = \mathsf{var}(y)$$

and thus

$$\underbrace{\operatorname{var}(y) - \operatorname{var}(\mathbb{E}[y|x_{\sim i}])}_{\operatorname{var}(y) = \mathbb{E}[\operatorname{var}(y|x_{\sim i})]$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

remaining variance if $x_{\sim i}$ were known

► total index:
$$S_{T_i} = \frac{\mathbb{E}[var(y|x_{\sim i})]}{var(y)} = 1 - \frac{var(\mathbb{E}[y|x_{\sim i}])}{var(y)}$$

$S_{T_i} = 0 \Leftrightarrow x_i$ non-important

⇐:

$$x_i \text{ non-import.} \Rightarrow \operatorname{var}(y|x_{\sim i}) = 0 \Rightarrow \mathbb{E}[\operatorname{var}(y|x_{\sim i})] = 0 \Rightarrow S_{\mathcal{T}_i} = 0$$

\Rightarrow :

$$S_{T_i} = 0 \Rightarrow \mathbb{E}[var(y|x_{\sim i})] = 0 \underset{var \geq 0}{\Rightarrow} var(y|x_{\sim i}) = 0 \Rightarrow$$

 $x_i \text{ not important}$

ANOVA (Reader's Digest version)

$$f(x) = f_0 + f_1(x_i) + f_2(x_{\sim i}) + f_{12}(x_i, x_{\sim i})$$

where

▶
$$f_0 = \int f(x) dx$$
,
▶ $f_1(x_i) = \int (f - f_0) dx_{\sim i}$, $f_2(x_{\sim i}) = \int (f - f_0) dx_i$
▶ f_{12} = remainder

 $\blacktriangleright\,$ above functions have zero average ${\Rightarrow}{\perp}$ ${\Rightarrow}\,$

$$\operatorname{var}(y) = \int (f(x) - f_0)^2 dx = \int f(x)^2 dx - f_0^2$$
$$= \underbrace{\int f_1^2 dx}_{\operatorname{var}(f_1)} + \underbrace{\int f_2^2 dx}_{\operatorname{var}(f_2)} + \underbrace{\int f_{12}^2 dx}_{\operatorname{var}(f_{12})}$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

another way to look at things

Sobol' indices can equivalently be defined as

$$S_i = rac{ ext{var}(f_1)}{ ext{var}(y)}, \qquad S_{\mathcal{T}_i} = rac{ ext{var}_{\mathcal{T}_i}}{ ext{var}(y)}$$

where

 $\operatorname{var}_{T_i} = \operatorname{var}(f_1) + \operatorname{var}(f_{12}) = \text{ total variance corresponding to } x_i$

exercise:

$$\operatorname{var}_{T_i} = \frac{1}{2} \iint (f(x) - f(x'))^2 \, dx \, dx'_i$$

where $x' = (x_1, ..., x_{i-1}, x'_i, x_{i+1}, ..., x_p)$.

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへぐ

another way to look at things

Sobol' indices can equivalently be defined as

$$S_i = rac{ ext{var}(f_1)}{ ext{var}(y)}, \qquad S_{\mathcal{T}_i} = rac{ ext{var}_{\mathcal{T}_i}}{ ext{var}(y)}$$

where

 $\operatorname{var}_{T_i} = \operatorname{var}(f_1) + \operatorname{var}(f_{12}) = \text{ total variance corresponding to } x_i$

exercise:

$$\operatorname{var}_{T_i} = \frac{1}{2} \iint (\overbrace{f(x) - f(x')}^{\frac{\partial f}{\partial x_i}(\hat{x})(x_i - x'_i)})^2 \, dx \, dx'_i$$

where $x' = (x_1, \dots, x_{i-1}, x'_i, x_{i+1}, \dots, x_p).$

◆□ ▶ ◆□ ▶ ◆ □ ▶ ◆ □ ▶ ● □ ● ● ● ●

back to the "calculus approach"

previous exercise \Rightarrow one can show (Sobol', Kucherenko, 2009)

$$S_{T_i} \leq \frac{1}{\pi^2 \operatorname{var}(y)} \underbrace{\int \left(\frac{\partial f}{\partial x_i}\right)^2 dx}_{\nu_i}$$

- \triangleright ν_i is another importance measure
- \triangleright ν_i is derivative based rather than variance based
- \triangleright ν_i may be simpler to compute than S_{T_i} if $\partial_{x_i} f$ is available
- if not, more approximations have to be considered
- parameter distributions are needed for both Sobol' and DGSMs (derivative based global sensitivity measures)

how to actually compute all this?

- ▶ lots of integrals of the type $\int g(x) dx_1 \dots dx_p$
- problems with 100's of parameters are the rule in practice, not the exception
- functions with 100's of variables that can be integrated through calculus are (really) the exception, not the rule
- \blacktriangleright \Rightarrow calculus is hopeless
- standard quadratures that work in dimension 2 or 3 are WAY too expensive in a high dimensional setting

we need something else!

Monte Carlo integration

- ► $X \sim U(0,1)$
- key observation

$$I = \int_0^1 g(x) \, dx$$
 can be regarded as $\mathbb{E}[g(X)] = \int_0^1 g(x) \, dx$

estimator:

$$I_N = \frac{1}{N} \sum_{i=1}^N g(X_i)$$

. .

where the X_i 's, i = 1, ..., N are N iid U(0, 1) RVs

▶ realizations of I_N are sample means of g(X)

$$\frac{1}{N}\sum_{i=1}^N g(x_i)$$

Monte Carlo: analysis

• estimates from I_N are exact on average:

$$\mathbb{E}[I_N] = \int_0^1 \frac{1}{N} \sum_{i=1}^N g(x) \, dx = \int_0^1 g(x) \, dx = I$$

 in what sense/how fast do realizations of *I_N* converge to *I*?
 var(*I_N*) = var(¹/_N ∑^N_{i=1} g(X_i)) = ¹/_{N²} var(∑^N_{i=1} g(X_i)) = ¹/_{N²} ∑^N_{i=1} var(g(X_i)) = ^V/_N where V = var(g(X)) = ∫¹₀ g²(x) dx - I²
 Chebyshev inequality ⇒ P (|*I_N* - *I*| > ^δ/_{√N}) ≤ ^V/_{δ²}, ∀δ > 0 is atheremeter.

in other words:

 $I_N \xrightarrow{P} I$ at rate $\mathcal{O}(N^{-1/2})$

(日) (日) (日) (日) (日) (日) (日)

Monte Carlo: analysis (II)

central limit theorem gives "error estimate"

$$I_N - I \approx \sqrt{rac{\mathcal{V}}{N}} \, \mathcal{N}$$

where \mathcal{N} is a N(0,1) RV

- ▶ slow rate $\mathcal{O}(N^{-1/2})$ but does not depend on dimension *p*
- various techniques can be used to speed up convergence

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

- variance reduction
- quasi Monte Carlo, etc...

additional challenges

- the parameters may be correlated
- the quantity of interest may be a vector rather than a scalar (see afternoon session) or a function ...
- f itself may be stochastic
- usually, parameter distributions are unknown (robustness?)

(日) (日) (日) (日) (日) (日) (日)

► sampling may be very expensive and/or the dimension very high ⇒ metamodels/surrogates

surrogates

- a surrogate \hat{f} approximates: $f \approx f$ in some sense
- \hat{f} is typically built from a "few" samples of f
- \hat{f} is (much) cheaper to evaluate than f
- if $\mu(f)$ is some importance measure of f, we hope

$$\mu(\hat{f})\approx \mu(f)$$

the above may be true for poor approximations of f (lots of work to be done here!)

(日) (日) (日) (日) (日) (日) (日)

example of surrogates

linear regression: fit the following model to data

$$f \approx \beta_0 + \beta_1 x_1 + \dots + \beta_p x_p$$

(日) (日) (日) (日) (日) (日) (日)

 \hat{f} can be the right hand side or only variables with "significant" β_i 's can be retained (screening)

- regression trees/forests, MARS
- Gaussian processes
- Polynomial Chaos Expansion
- ▶ and many more...

tutorial summary

- variance based methods work well but may be expensive
- derivative based methods (or elementary effects) tend to be cheaper
- (some) surrogate models can be used for dimension reduction
- sometimes, simple models (linear regression) work shockingly well!
- sometimes, they don't...
- our quantity of interest y is usually not directly what comes out of a "disciplinary solver" but depends on it
- ignoring correlations may be disastrous
- taking correlations into account is hard
- there is much to do: join us!