

Modern statistical inference in complex biological systems

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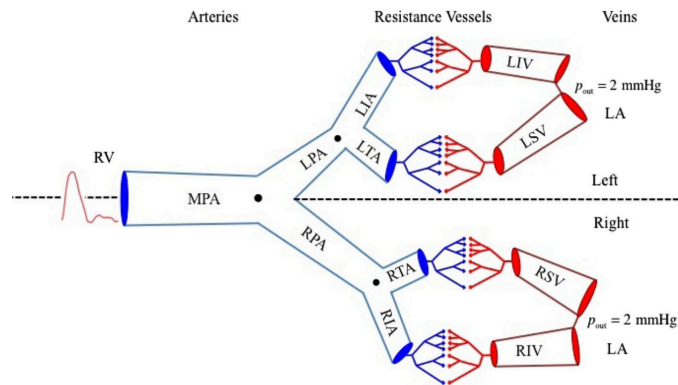
School of Mathematics
& Statistics





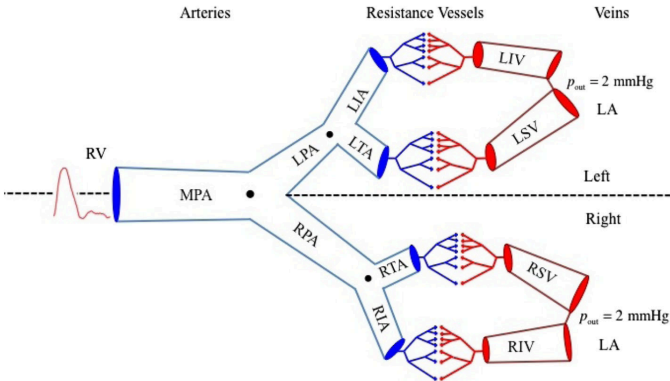


Dynamical System



$$\frac{\partial q}{\partial t} + \frac{\partial}{\partial x} \left(\frac{q^2}{A} \right) + \frac{A}{\rho} \frac{\partial p}{\partial x} = - \frac{2\pi\nu r}{\delta} \frac{q}{A}$$

Dynamical System



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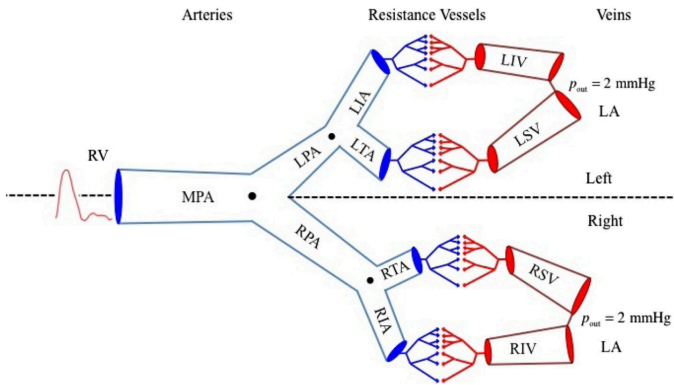
Experimental data



Model prediction

Objective function

Dynamical System



$$\frac{\partial q}{\partial t} + \frac{\partial}{\partial x} \left(\frac{q^2}{A} \right) + \frac{A}{\rho} \frac{\partial p}{\partial x} = - \frac{2\pi\nu r}{\delta} \frac{q}{A}$$



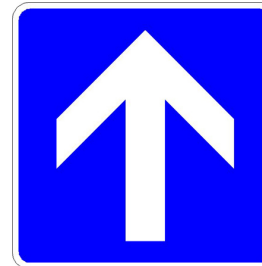
Closed-form solution

Experimental data



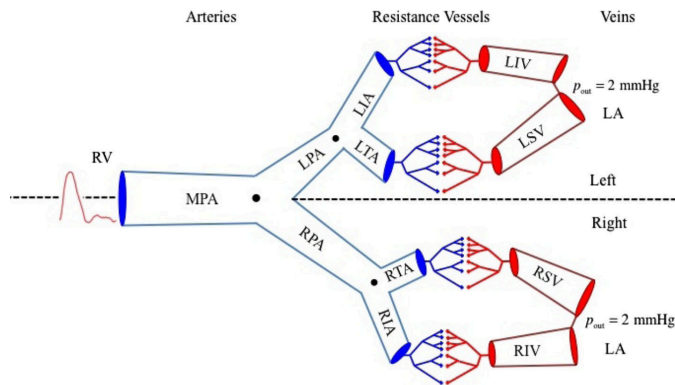
Model prediction

Objective function



Closed-form solution

Dynamical System



$$\frac{\partial q}{\partial t} + \frac{\partial}{\partial x} \left(\frac{q^2}{A} \right) + \frac{A}{\rho} \frac{\partial p}{\partial x} = - \frac{2\pi\nu r}{\delta} \frac{q}{A}$$



Closed-form
solution

Experimental data



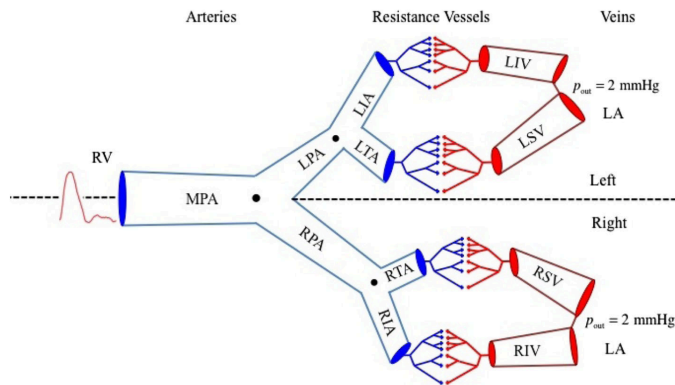
Model prediction

Objective function



Analytically
intractable

Dynamical System



$$\frac{\partial q}{\partial t} + \frac{\partial}{\partial x} \left(\frac{q^2}{A} \right) + \frac{A}{\rho} \frac{\partial p}{\partial x} = - \frac{2\pi\nu r}{\delta} \frac{q}{A}$$

Experimental data



Model prediction

Objective function



Analytically
intractable



Analytically
intractable

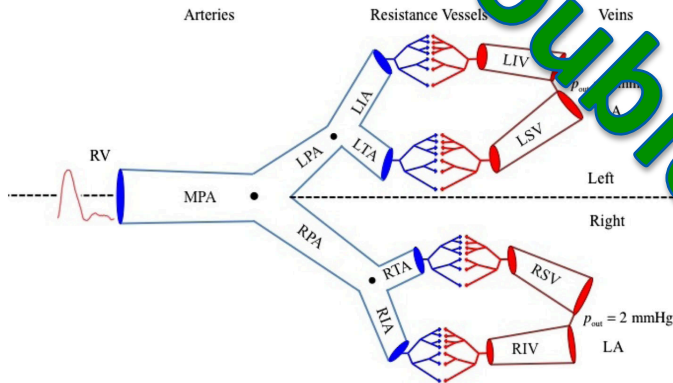
Dynamical System

Experimental data



Model prediction

Objective function



$$\frac{\partial q}{\partial t} + \frac{\partial}{\partial x} \left(\frac{q^2}{A} \right) + \frac{A}{\rho} \frac{\partial p}{\partial x} = - \frac{2\pi\nu r}{\delta} \frac{q}{A}$$



Analytically
intractable



Analytically
intractable

Double intractable

Overview

Statistical emulation

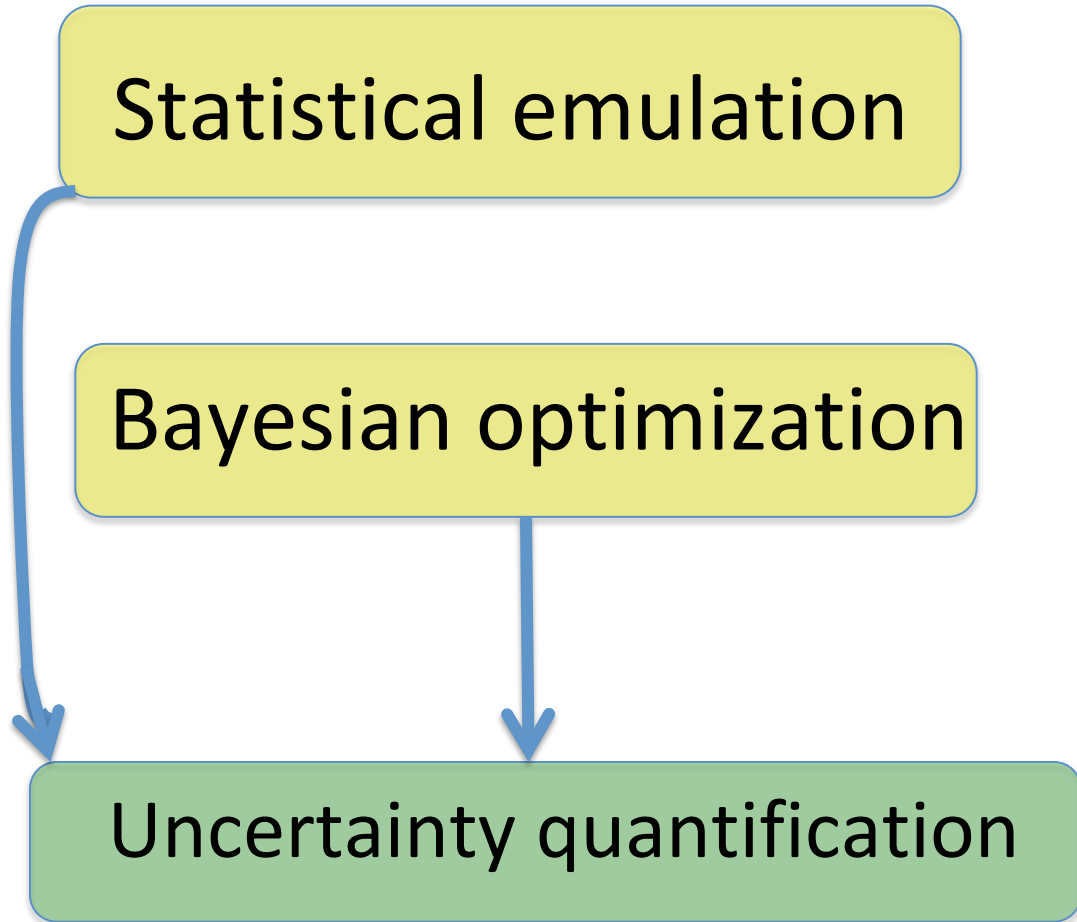
Bayesian optimization

Overview

Statistical emulation

Bayesian optimization

Uncertainty quantification



Overview

Statistical emulation

Gaussian
processes

Bayesian optimization

Uncertainty quantification

